

VISUALIZATION OF SOUND AS A CONTROL INTERFACE

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ABSTRACT

We here introduce the opportunity of using visualization of sound as a control interface, for artistic live performance as well as for new digital audio effects developments. Two different approaches are exposed. The first access consists in using Jitter video matrixes for mapping the variables parameters of sound processing, with the coordinates of any controller in a 2D plan or 3D space. The second access proposes a visualization of sound that modifies sound data by processing the data of the image itself with its own graphical properties. Exploring this kind of « transducting » relation between visual and audio may be interesting for artistic creation domain using virtual surroundings; it may cause an interest for the real time digital audio, for audiovisual mixing and new interfaces for sound design. Besides, it points the opportunity of developing 3D control interfaces for audio and visual processes.

1. INTRODUCTION

Beyond scientific graphical representations of sound, such as waveforms or spectrograms, there is no objective representation of sound phenomenon, no machine to visualize sound. There are only subjective, more or less metaphorical representations, in heterogeneous sound or musical context. Visualizing the sound phenomenon, after the real time digital audio flow coupled to real time video data flow, such as a programming software as Max/MSP/Jitter [1] can offer, consists as far as a representation, to visually mark some of the sound qualities, to offer a better listening, a better perception, and real time operation on sound. Hence, we are inverting the ordinary relation between audio and visual, by using visualization of sound as a control interface of sound perceptive parameters, indeed exploiting the graphical properties of sound visualization to process sound itself.

2. VISUAL INTERFACE TO CONTROL SOUND

Considering our previous research on self-centered perception of sound spaces [2][3][4][5], we have decided to link some of its characteristics with our study of visualization of sound as an interface. Assuming that a musical piece can be seen as a set of parameters varying in time (we are referring here to what we

called earlier “intentional parameters”), a deterministic musical piece can be represented as follows:

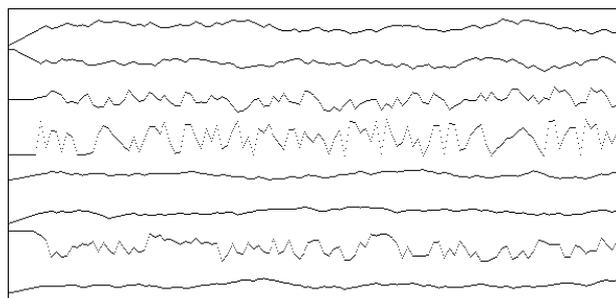


Figure 1. A time/amplitude representation of the evolution of 8 parameters

Here, the time line is explicit, and proposing this type of visualization modifies our perception of the form of the piece (because all evolutions past and future can be seen at the same time). Thus we have decided to let the user free to imprint his own timeline to the piece. Referring conceptually to the Wave Terrain [6], we have decided that a terrain would represent each parameter. The terrain will appear on screen as a monochrome picture, the value of the parameter being mapped with the intensity of the colour. A terrain set (the superposition of each terrain) would result, on which the user could move, outputting the parameters values at the point where he is located.

Thanks to the Max/MSP/Jitter programming environment, we have developed software to illustrate these concepts, using the OpenGL set of Jitter objects.

2.1. Writing interface overview

The main use of this interface is to create quickly a terrain set by drawing colored shapes within a reduced matrix (a tenth of the final matrix).

One has to select one of the three planes (red, green and blue) and set the intensity of the corresponding colour and then draw directly onto the terrain window (the left one, on fig.2). It's possible to use an interpolating filter in order to smooth the terrain for the final matrix (the result of the interpolation appears in the right window on fig. 2). Thumbnails for each plane are available on the left side. When done, the resulting matrix has to be exported in the Jitter matrix format in order to be loaded later in the visualization interface.

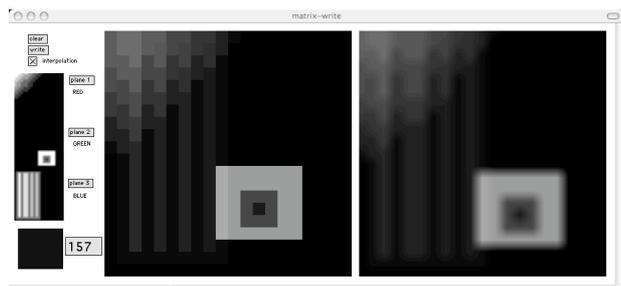


Figure 2. A software interface for designing terrain sets.

The visualization interface is a minimal 3D environment consisting in a textured ground on which it is possible to move thanks to mouse. The 3D engine is the same as the one used in prior works *Egosound* [7] and *La Terre ne se meut pas* [8].

For an (x,y) set of cartesian coordinates corresponding to the location of the user on the ground, we have a set of parameters $R(x,y)$, $G(x,y)$ and $B(x,y)$ according to the matrix (x,y) cell values. From now, we will only consider one parameter $P(x,y)$, because of the greyscale constraint of the presentation. In the illustration below, we can see a terrain (one parameter) and then, its projection in the visualization interface.

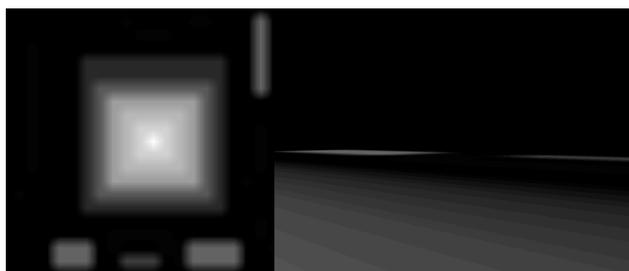


Figure 3. A terrain seen "from above" (left) and this terrain used as a texture in the visualization interface (right)

From a trajectory $T: t \rightarrow (x(t),y(t))$ (a set of (x,y) coordinates varying in time), a time-varying $P(t)$ will result. We just have seen in a very simple way how time and space are linked, and how we can recover a time-varying expression of a parameter from its spatial distribution. The following screenshots show the same terrain, on which are drawn two different trajectories (clockwise). Thus, we have two different evolutions of the parameter, represented first with colour intensity, then as usual amplitude/time graphs.

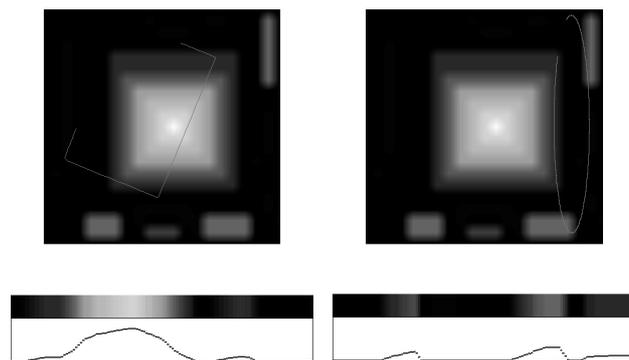


Figure 4. Two different trajectories on the same terrain and the resulting amplitude/time representations of the parameters evolution.

Therefore, we can easily imagine that, given a terrain there is an infinity of possible dynamic evolutions for its associated parameter. Of course, given a fixed trajectory, depending on the variation of the speed along this trajectory, many different results can be obtained.

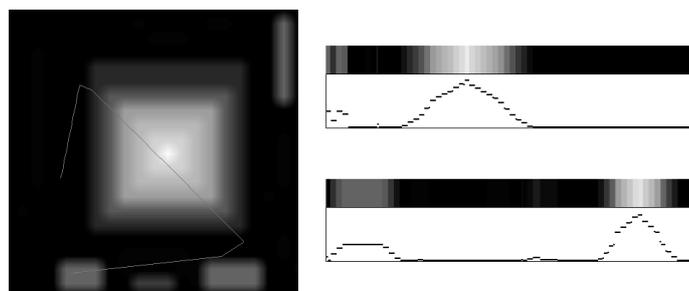


Figure 5. The same trajectory (clockwise) with different speed variation and the associated evolution of parameters

Moreover, this has been discussed in the case of a single parameter, and can be extended to the case of sets of many parameters. Although there might be infinities of musical results associated with a single terrain set, it doesn't mean that the piece (even if interactive) escapes to the composer intentions. On the contrary, we will show briefly how the design of a terrain can determine global trends. The only thing known for sure is that the movement on the terrain is continuous: the (x,y) pairs will evolve contiguously (the user cannot "jump" from one point to another). Here are two examples of strategies for terrain design. On the left (fig. 6), the terrain as been designed with care of continuity, therefore, whatever trajectory or speed will be used onto it, the associated result will be a continuously evolving parameter, whether on the right, no interpolation has been used, and small shapes have been drawn, the parameter will then evolve with discontinuities. Thus, one can determine trends in a certain way and leaving room for variations.

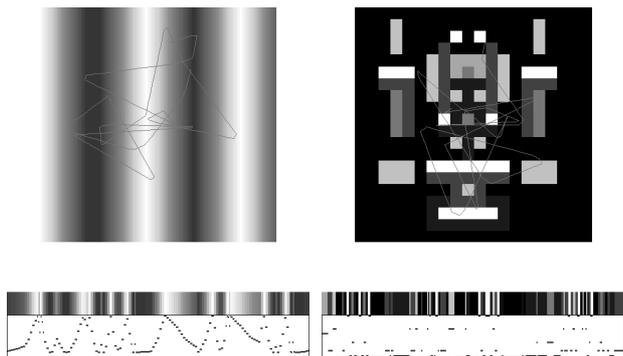


Figure 6. Two different terrain design strategies

One of the main interests of seeing parameters as terrains is that we can use many different software to create 2D pictures to be considered as terrains. The one we have presented has been developed for an almost didactic purpose and has the advantage of being integrated in the Jitter environment. Of course, we could use software such as Photoshop [9], Scilab [10] or terrain editors like the Parametric Terrain Editor (PTE) [11], which has been especially developed for terrain design in 3D software. Here's an example of terrain designed with PTE:

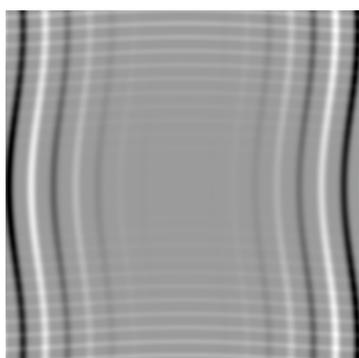


Figure 7. Example of a terrain designed with the Parametric Terrain Editor.

Though the visualization interface is based on an immersive 3D environment, we have only dealt with 2D geometry. It's possible to imagine that the value of a parameter might be used to set both the colour intensity and the z coordinate of the corresponding point on the terrain:

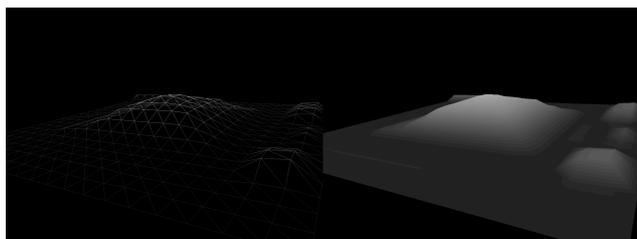


Figure 8. Two views of a 3D terrain

However, we are working on the realization of tools for "real" 3D design, but it points out many conceptual problems (though the visualization interface is ready by now for 3D movements). We can also imagine time-varying terrains (videos instead of still images) setting a global timeline for the interactive piece, so that sequences might not be experienced twice, for example.

3. GRAPHICAL TRANSFORMATION OF AN ANALYZED SOUND

We have presented visual interfaces that allow the user to control high-level sound parameters. We will now present a visual interface based on a formal representation of sound. Our aim is to modify the sound helped by a graphical interface of the sound itself after analyze. In order to manipulate the sound graphically, we apply a STFT to a stream of input samples and draw it on a visual window. Scaled to a logarithmic view, the sonogram is then graphically modifiable. The resulting matrix of this transformation is then synthesized.

The window representing the sound is a time-frequency-amplitude representation. Graphical transformation would necessarily transform sound according to these three parameters. Considering the visual window as a drawing interface, the user modifies the STFT synthesized in real-time. We developed mainly two ways of manipulating the visual STFT.

3.1. Global transformations

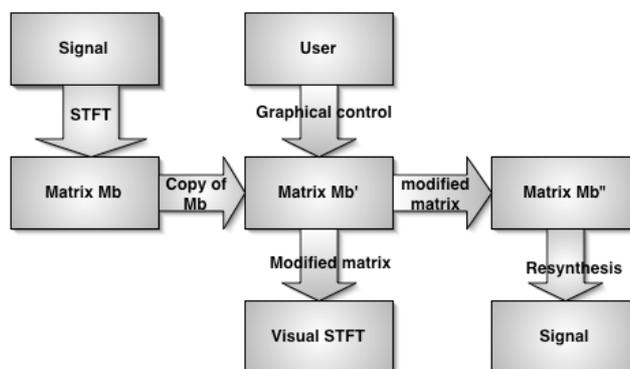


Figure 9. The user controls the matrix with graphical operations. Transformations are applied on both image and sound.

We present the different modifications according to the main transformation they concern between time, frequency and amplitude. Some similar operations have been described [8]. They are usually obtained by a phase vocoder, with functions that modify partials. Regarding sound as an image allows to apply graphical transformations that have not been implemented with a phase vocoder. The interface is transparent due to the formal relation between the image and the sound. Graphical transformations are obtained with standard externals of the Jitter library. Based on Musical transformations using additive

analysis/re-synthesis of the Computer Music Tutorial[12], we describe the transformations obtained with a graphical control.

3.1.1. Time transformation

Considering that the abscissa axe represents the time, all the graphical modifications of this axe will modify the sound.

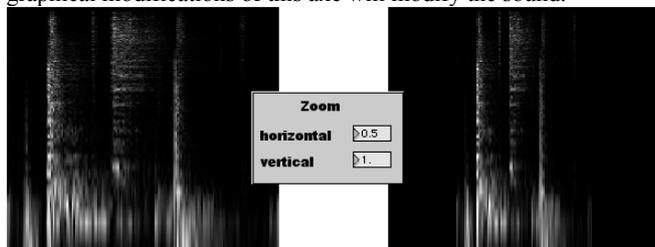


Figure 10. The right image is a zoom out of the left image : the sound is time-reduced

Time scaling (see figure 10): Zoom in or zoom out. A zoom in causes a graphical interpolation that sounds like an ordinary deceleration. A zoom out causes a graphical reduction that sounds like acceleration. Due to the time limit of the matrix, the zoom transformation occurs loss of information. While zoom in, output parts of the matrix are lost. While zoom out, image is reduce, thus data are lost too.

Non-linear synthesis (see figure 11): The user can control the time position of the STFT synthesis. The user controls the index of a vector of the matrix, corresponding to a single vertical line of the image. The synthesis thus concerns only 512 samples (0.011"). The time line can be modified by a control of the index. For example, a broken time line can be use to control the STFT synthesis. In the particular case of the synthesis of a single line, the repetition of 512 samples is a very textured, continuous sound.

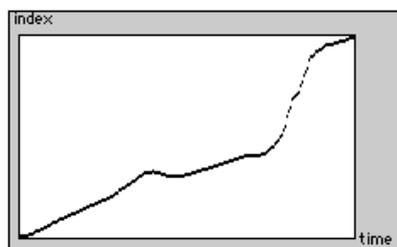


Figure 11. The ordinate axe represents the index of the synthesized vector. A non-linear curve causes a non-linear time-play of the sound.

3.1.2. Frequency transformation

Considering that the ordinate axe represents the frequency, all the graphical modifications of this axe will modify the sound.

Spectrum shifting: Shifting the image up or down. The modified sound result of the addition of a factor n to all partials. This shifting can sounds differently according to the algorithm used for scaling the STFT

Spectrum inversion: Vertical inversion of the image. Obtained by a vertical zoom of a factor -1 (Low frequencies take place of high frequencies, and vice versa)

Spectrum zoom: Zoom in or zoom out of the ordinate axe. In a zoom in operation, the frequency domain zoomed is scaled to a

larger frequency domain. Border information and precision are lost due to the finite definition of the STFT. In a zoom out operation, the frequency domain is restricted. Data are scaled to a lower domain.

Spectrum rotation (see fig 12): Rotation of the image based on an anchor point. It causes a linear frequency variation, ascendant or descendant according to the sense of rotation. For a $\pi/2$ rotation, a transient attack becomes a continuous sound, and vice versa.

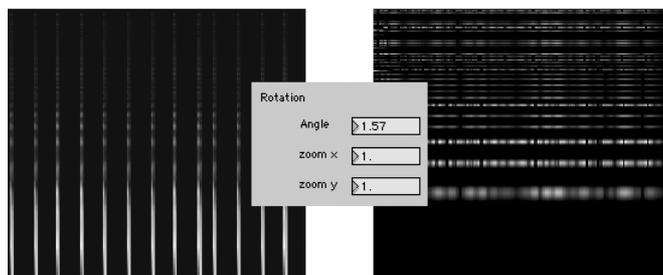


Figure 12. The left image is the STFT of a digital click. Transient attack becomes continuous sound on the right image after a $\pi/2$ rotation.

3.1.3. Amplitude transformation

Considering that amplitude is a function of the luminance of the image, all the graphical transformation on luminance would influence the sound.

Kind of reverb: Apply a blur transformation to the matrix

Saturation (see fig. 13): Saturation / desaturation of light. The matrix is multiply by a n factor

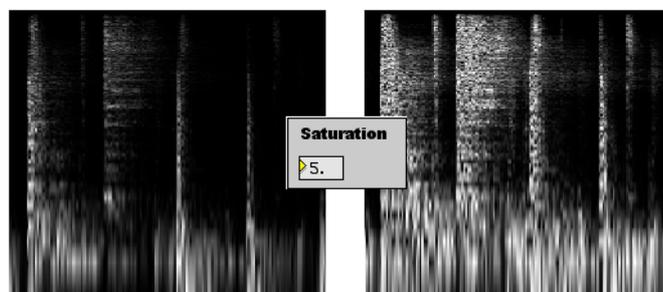


Figure 13. The saturation factor enhances the luminance of the image. For small values, the result (on the left) sounds much like amplification.

The limits of this approach are that this sonic design can be reduce to the drawing of a FFT. Create sounds with this process encounter graphical needs imposed by the time-frequency representation of the FFT.

3.2. Local transformations

In order to apply local transformations, we use a transfer matrix that allows the user to draw graphic controls. The transfer matrix uses the R, G, B layers as different planes of parameters. While the user draws on the transfer matrix, the STFT is processed with

each plan of parameters, according to different ways that we will develop now.

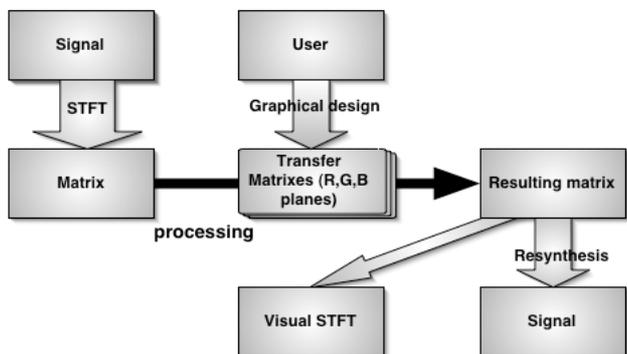


Figure 14. The three planes of the designed image process the basic matrix.

We consider that the abscissa axe of the transfer matrix represents time the same way it is represented in the STFT. All the transformations we draw on this interface will affect the sound in time.

The first transformation we program concerns amplitude. We use the red plan of the matrix transfer as a frequency filter. The value of each cell, between 0 and 255, is scaled to a multiplying k factor between 0 and 1. The STFT matrix is then multiply by the red matrix to obtain an amplitude-filtered matrix that can be synthesized.

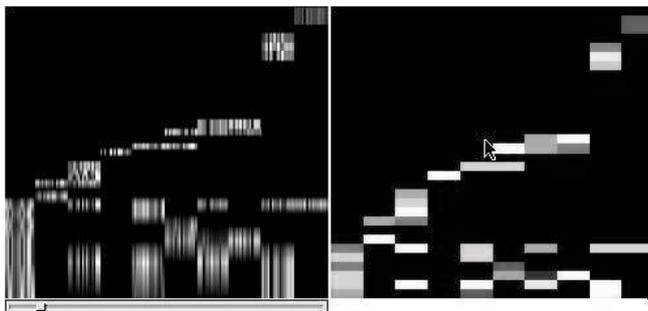


Figure 15. The right image is the interface of the transfer matrix. The left image is the result of the basic STFT multiply by the transfer matrix

The green plan is used for a spectral delay. Each cell of the matrix, also scaled to [0..1], will process the STFT according to a jitter external, jit.scanslide. The STFT bins will be delayed graphically according to the green bins of the transfer matrix. That causes a spectral delayed signal.

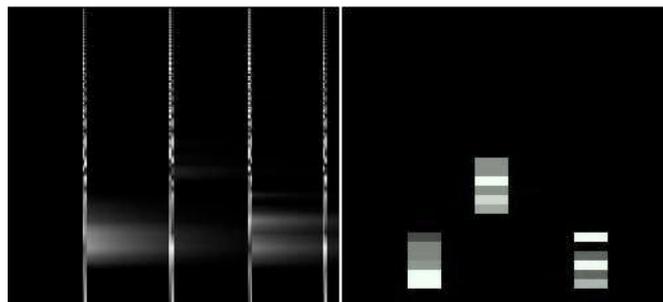


Figure 16. Green coloured cell (right image) cause a delay on the STFT (left image)

These transformations have been implemented in the *Sonos* software. The blue plan has not yet been devoted to a specific effect. This approach of sound transforming by a mapping of graphic properties to a musical purpose shows a great potential. Image processing used for video-jokers can control musical parameters via this interface.

4. CONCLUSION

We have exposed two different and maybe complementary ways of working with visualization of sound in order to offer new tools of operations on sound processing. We are applying the products of our research to experimental artistic creation such as audio and video live electronic or interactive choreographies, and other expressions that are dealing with “transducting” relations between image and sound. Such a tools, now at the beginning of the development, may concern the digital audio effect software, the audio and visual mixing applications. They suggest imagining 3D Interfaces, at least to surpass traditional representation. This maybe the subject of our future works.

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